

02/02

Prp Let  $\{v_1, \dots, v_d\} \subseteq V$  be a basis  $v \in V$ .

Then,  $\exists ! \alpha_1, \dots, \alpha_d \in \mathbb{R}$  s.t.  $v = \alpha_1 v_1 + \dots + \alpha_d v_d$ .

$$\begin{array}{l} \swarrow \\ [v]_{\mathcal{B}} = \begin{bmatrix} \alpha_1 \\ \vdots \\ \alpha_d \end{bmatrix} \\ \swarrow \\ \text{coordinates} \end{array} \quad \begin{array}{l} \uparrow \\ \text{dimension} \end{array}$$

$$V := \{y \in C^\infty(\mathbb{R}) : y'' + y = 0\}$$

$\mathcal{C} := \{e^{ix}, e^{-ix}\}$  is a basis for

$$V, \cos(x) \in V,$$

$$[\cos(x)]_{\mathcal{C}} = \begin{bmatrix} \alpha_1 \\ \alpha_2 \end{bmatrix}$$

$$\begin{array}{l} e^{ix} = \cos(x) + i \sin(x) \leftarrow \text{Euler's formula} \\ e^{-ix} = \cos(x) - i \sin(x) \end{array} = \begin{bmatrix} 1/2 \\ 1/2 \end{bmatrix}$$

$$\sin(x) = \frac{1}{2i} e^{ix} - \frac{1}{2i} e^{-ix}$$

$$[\sin(x)]_{\mathcal{C}} = \begin{bmatrix} 1/2i \\ -1/2i \end{bmatrix}$$

$$[e^{ix}]_{\mathcal{C}} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \quad [e^{-ix}]_{\mathcal{C}} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$V := \mathbb{R}^3$$

$$\mathcal{B} := \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\} \leftarrow \text{standard basis}$$

$$\mathcal{C} := \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix} \right\}$$

$$[v]_{\mathcal{B}} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$$

$$[v]_{\mathcal{C}} = \begin{bmatrix} 1 & 1 & 1 & 1 & 1 \\ 0 & 1 & -1 & 1 & 2 \\ 0 & 1 & 1 & 1 & 3 \end{bmatrix}$$

## Coordinates of linear transformations

Prop Let  $T: V_1 \rightarrow W$  be a lin. trans

$\mathcal{B} = \{b_1, \dots, b_d\}$  basis for  $V$ .

$\mathcal{C} = \{c_1, \dots, c_e\}$  basis for  $W$ .

Then,  $\exists!$  exd matrix  $[T]_{\mathcal{C} \leftarrow \mathcal{B}}$  s.t.

$$[T(v)]_{\mathcal{C}} = [T]_{\mathcal{C} \leftarrow \mathcal{B}} [v]_{\mathcal{B}} \quad \forall v \in V$$

Furthermore,

$$[T]_{\mathcal{C} \leftarrow \mathcal{B}} = \left[ [T(b_1)]_{\mathcal{C}}, \dots, [T(b_d)]_{\mathcal{C}} \right]$$

$\text{id}_V: V \rightarrow V$

$\mathcal{B}, \mathcal{C}$  diff. bases for  $V$

$[\text{id}_V]_{\mathcal{C} \leftarrow \mathcal{B}}$  change of basis matrix

$$[v]_{\mathcal{C}} = [\text{id}]_{\mathcal{C} \leftarrow \mathcal{B}} [v]_{\mathcal{B}}$$

$$[T \circ S]_{\mathcal{D} \leftarrow \mathcal{B}} = [T]_{\mathcal{D} \leftarrow \mathcal{C}} [S]_{\mathcal{C} \leftarrow \mathcal{B}}$$

$V := \{y \in C^\infty(\mathbb{R}) : y'' + y = 0\}$

$T: V \rightarrow V, T(f) = f'$

$\mathcal{B} := \{\cos(x), \sin(x)\}, \mathcal{C} = \{e^{ix}, e^{-ix}\}$

We can calculate:

$$\left[ \frac{d}{dx} \right]_{\mathcal{B} \leftarrow \mathcal{B}} = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \quad \left[ \frac{d}{dx} \right]_{\mathcal{C} \leftarrow \mathcal{B}} = \begin{bmatrix} \frac{d}{dx} \cos(x) \\ \frac{d}{dx} \sin(x) \end{bmatrix}_{\mathcal{C}}$$

$$\left[ \frac{d}{dx} \right]_{\mathcal{B} \leftarrow \mathcal{C}} = \begin{bmatrix} [ie^{ix}] & [ie^{-ix}] \\ [i] & [-i] \\ [-1] & [1] \end{bmatrix} \quad \left[ \frac{d}{dx} \right]_{\mathcal{C} \leftarrow \mathcal{C}} = \begin{bmatrix} [-\frac{1}{2}i] & [\frac{1}{2}i] \\ [ie^{ix}] & [ie^{-ix}] \\ [i] & [0] \\ [0] & [-i] \end{bmatrix}$$

§ 1.9

$$T: \mathbb{R}^2 \rightarrow \mathbb{R}^4$$

Standard Matrix: Basis of

$$\left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix} \right\}$$

$$T(e_1) = \begin{bmatrix} -3 \\ 1 \\ 3 \\ 1 \end{bmatrix}, \quad T(e_2) = \begin{bmatrix} 5 \\ -2 \\ 0 \\ 0 \end{bmatrix}$$

$$[T]_{\mathcal{B}_4 \leftarrow \mathcal{B}_2} = \left[ [T(e_1)]_{\mathcal{B}_4}, [T(e_2)]_{\mathcal{B}_4} \right]$$

$$= \left[ \begin{bmatrix} -3 \\ 1 \\ 3 \\ 1 \end{bmatrix}, \begin{bmatrix} 5 \\ -2 \\ 0 \\ 0 \end{bmatrix} \right]$$

$T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ , rotation by  $\theta$

$$[T] = \begin{bmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{bmatrix}$$

$$T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

$$T(e_1) = e_1, \quad T(e_2) = e_2 + 2e_1$$

$$[T] = \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix}$$

$\mathbb{R}[x]/(x^3)$  - polynomials of deg at most 2

↑ set  $x^3 = 0$ . Basis:  $\{1, x, x^2\}$

$\mathbb{R}[x] \leftarrow$  all polynomials