

15.10 Change of Variables in Multiple Integrals

Flashback:

$$\int_a^b f(x) dx = \int_c^d f(g(u)) g'(u) du \quad \begin{array}{l} x=g(u) \\ dx=g'(u) du \end{array} \quad \begin{array}{l} c=g(a) \\ d=g(b) \end{array}$$

Also written as $\int_a^b f(x) dx = \int_c^d f(x(u)) \frac{dx}{du} du$

Transformations of \mathbb{R}^2 :

Consider a change of variables given by a transformation T from the uv -plane to the xy -plane:

$$T(u, v) = (x, y) \quad \text{where} \quad x = g(u, v) \quad \& \quad y = h(u, v)$$

* Assume g & h have continuous partial derivatives

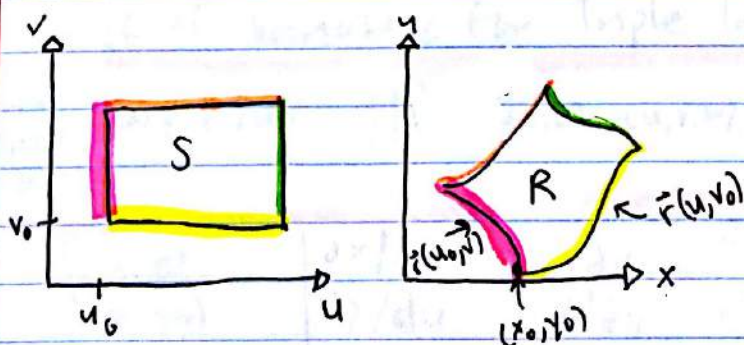
T maps a region S in the uv -plane to a region R in the xy -plane. ($\partial S \rightarrow \partial R$)

The Jacobian of T :

Let S be a small rectangle in the uv -plane with lower left corner (u_0, v_0) and sides $\Delta u, \Delta v$.

Let $R = T(S)$, the image of S , which is a region in the xy -plane. One of its boundary pts is $T(u_0, v_0) = (x_0, y_0)$
 $\Rightarrow x_0 = g(u_0, v_0), \quad y_0 = h(u_0, v_0)$

The vector $\vec{r}(u, v) = g(u, v)\hat{i} + h(u, v)\hat{j}$ is the position vector of R .



Tangent vector at (x_0, y_0)
(lower side of S) is:

$$\vec{r}_u = g_u(u_0, v_0)\hat{i} + h_u(u_0, v_0)\hat{j} = \begin{bmatrix} \frac{dx}{du} \hat{i} + \frac{dy}{du} \hat{j} \end{bmatrix}$$

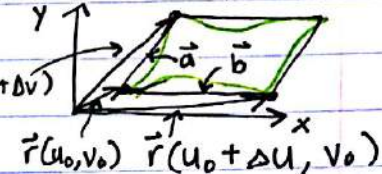
left side of S :

$$\vec{r}_v = \begin{bmatrix} \frac{dx}{dv} \hat{i} + \frac{dy}{dv} \hat{j} \end{bmatrix}$$

\vec{r}_u = partial derivative w/ respect to u

Note that R can be approximated by a parallelogram with adjacent sides $\vec{a} = \vec{r}(u_0 + \Delta u, v_0) - \vec{r}(u_0, v_0)$ and $\vec{b} = \vec{r}(u_0, v_0 + \Delta v) - \vec{r}(u_0, v_0)$

But, $\vec{r}_u = \lim_{\Delta u \rightarrow 0} \frac{\vec{r}(u_0 + \Delta u, v_0) - \vec{r}(u_0, v_0)}{\Delta u}$



so $\vec{a} \approx \Delta u \vec{r}_u$. Similarly, $\vec{b} \approx \Delta v \vec{r}_v$

We can approximate R by the parallelogram with adjacent vectors $\Delta u \vec{r}_u$ and $\Delta v \vec{r}_v$. We do this by

$$|\Delta u \vec{r}_u \times \Delta v \vec{r}_v| = \Delta u \Delta v |\vec{r}_u \times \vec{r}_v|$$

So we have:

$$\vec{r}_u \times \vec{r}_v = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial x}{\partial u} & \frac{\partial y}{\partial u} & 0 \\ \frac{\partial x}{\partial v} & \frac{\partial y}{\partial v} & 0 \end{vmatrix} = \left(\frac{\partial x}{\partial u} \frac{\partial y}{\partial v} - \frac{\partial x}{\partial v} \frac{\partial y}{\partial u} \right) \hat{k}$$

Note that $\begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial y}{\partial u} \\ \frac{\partial x}{\partial v} & \frac{\partial y}{\partial v} \end{vmatrix} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix}$

This determinant is called the Jacobian of T .

It is denoted by $\frac{\partial(x, y)}{\partial(u, v)}$. So $A(R) \approx \left| \frac{\partial(x, y)}{\partial(u, v)} \right| \Delta u \Delta v$.

Change of Variables for Double Integrals:

$$\iint_R f(x, y) dA = \iint_S f(x(u, v), y(u, v)) \left| \frac{\partial(x, y)}{\partial(u, v)} \right| du dv$$

Change of Variables for Triple Integrals:

$$\iiint_R f(x, y, z) dV = \iiint_S f(x(u, v, w), y(u, v, w), z(u, v, w)) \left| \frac{\partial(x, y, z)}{\partial(u, v, w)} \right| du dv dw$$

$$\frac{\partial(x, y, z)}{\partial(u, v, w)} = \begin{vmatrix} \partial x / \partial u & \partial x / \partial v & \partial x / \partial w \\ \partial y / \partial u & \partial y / \partial v & \partial y / \partial w \\ \partial z / \partial u & \partial z / \partial v & \partial z / \partial w \end{vmatrix}$$

Special Case: Integration in Polar Coordinates:

$$\begin{aligned} x &= r \cos \theta \\ y &= r \sin \theta \end{aligned}$$

$$\text{Jacobian: } \begin{vmatrix} \partial x / \partial r & \partial x / \partial \theta \\ \partial y / \partial r & \partial y / \partial \theta \end{vmatrix}$$

$$= \begin{vmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{vmatrix}$$

$$= r \cos^2 \theta + r \sin^2 \theta = \boxed{r}$$

$$\iint_R f(x, y) dA = \iint_S f(r \cos \theta, r \sin \theta) r dr d\theta \quad \text{!!!}$$

Special Case: Integration in Cylindrical Coordinates:

$$\begin{aligned} x &= r \cos \theta \\ y &= r \sin \theta \\ z &= z \end{aligned}$$

$$\text{Jacobian: } \begin{vmatrix} \partial x / \partial r & \partial x / \partial \theta & \partial x / \partial z \\ \partial y / \partial r & \partial y / \partial \theta & \partial y / \partial z \\ \partial z / \partial r & \partial z / \partial \theta & \partial z / \partial z \end{vmatrix}$$

$$= \begin{vmatrix} \cos \theta & -r \sin \theta & 0 \\ \sin \theta & r \cos \theta & 0 \\ 0 & 0 & 1 \end{vmatrix} = \boxed{r}$$

$$\iiint_R f(x, y, z) dV = \iiint_S f(r \cos \theta, r \sin \theta, z) r dz dr d\theta \quad \text{!!!}$$

Special Case: Integration in Spherical Coordinates

$$\begin{aligned} x &= \rho \sin \phi \cos \theta \\ y &= \rho \sin \phi \sin \theta \\ z &= \rho \cos \phi \end{aligned}$$

$$\text{Jacobian: } \begin{vmatrix} \partial x / \partial \rho & \partial x / \partial \theta & \partial x / \partial \phi \\ \partial y / \partial \rho & \partial y / \partial \theta & \partial y / \partial \phi \\ \partial z / \partial \rho & \partial z / \partial \theta & \partial z / \partial \phi \end{vmatrix}$$

$$\iiint_R f(x, y, z) dV = \iiint_S f(\rho \sin \phi \cos \theta, \rho \sin \phi \sin \theta, \rho \cos \phi) \rho^2 \sin \phi d\rho d\theta d\phi \quad \text{!!!}$$

$$= \begin{vmatrix} \sin \phi \cos \theta & -\rho \sin \phi \sin \theta & \rho \cos \phi \cos \theta \\ \sin \phi \sin \theta & \rho \sin \phi \cos \theta & \rho \cos \phi \sin \theta \\ \cos \phi & 0 & -\rho \sin \phi \end{vmatrix}$$

$$= -\rho^2 \sin \phi, \quad |-\rho^2 \sin \phi| = \boxed{\rho^2 \sin \phi}$$

Special Case: Linear Transformations of the Plane

Shift & Stretch:

$x = au + k$ ← stretches by fact. of a in horizontal direc.

$y = bv + l$ ← stretches by fact. of b in vertical direc.

so we should expect the areas to be $\times |ab|$

$$\text{Jacobian: } \begin{vmatrix} a & 0 \\ 0 & b \end{vmatrix} = ab, \quad \iint_R f(x,y) dA = \iint_S f(au+k, bv+l) |ab| du dv$$

Special case: Linear Transformations of Space - Shifts & Stretch

$$x = au + k$$

$$y = bv + l$$

$$z = cw + m$$

$$\text{Jacobian: } \begin{vmatrix} a & 0 & 0 \\ 0 & b & 0 \\ 0 & 0 & c \end{vmatrix} = abc$$

$$\iiint_R f(x,y,z) dV = \iiint_S f(au+k, bv+l, cw+m) |abc| du dv dw.$$